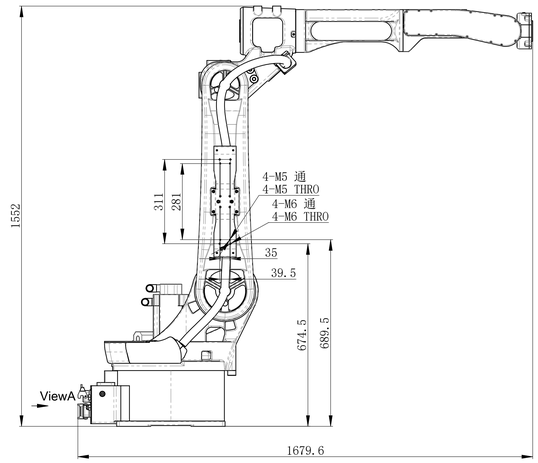
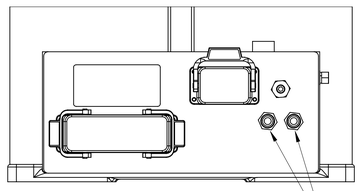
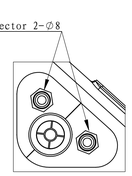
# 设备安装面尺寸
# Equipment mounting face dimension

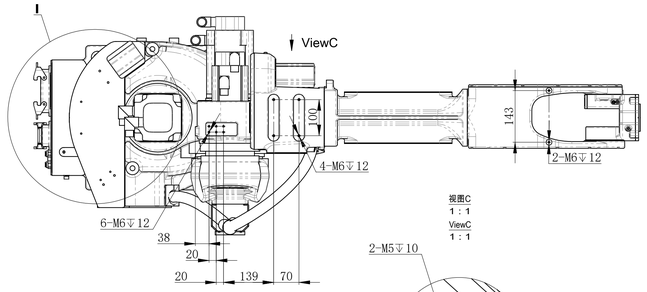



视图A
1 : 2.5
ViewA
1 : 2.5



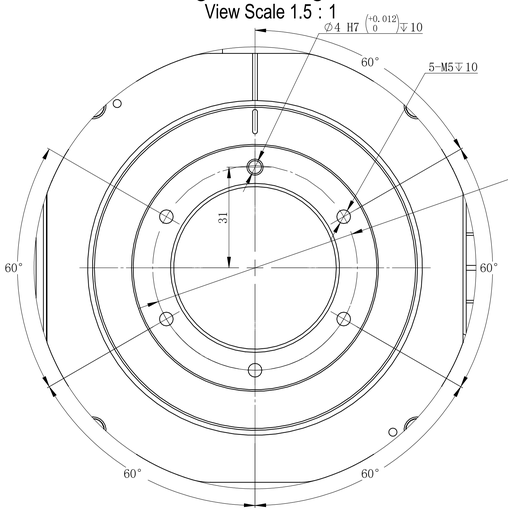

视图B
1 : 2
ViewB
1 : 2

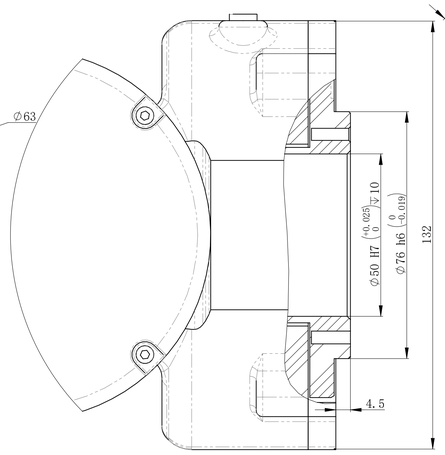


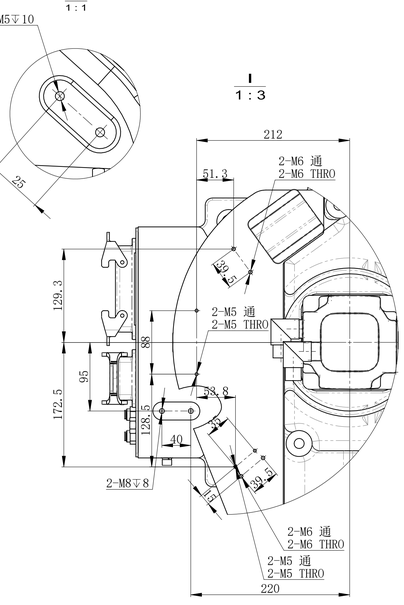




视图C
1 : 1
ViewC
1 : 1

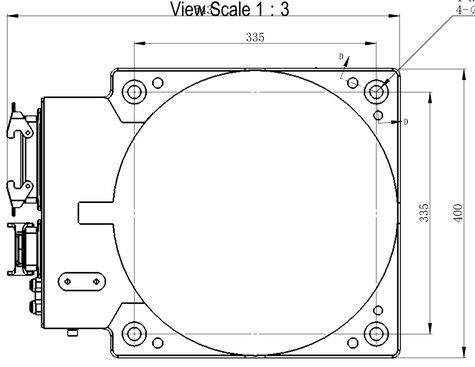
# 末端法兰安装接口
# End flange mounting dimension
View Scale 1.5 : 1

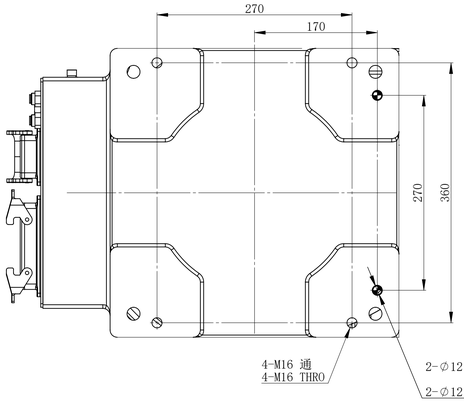


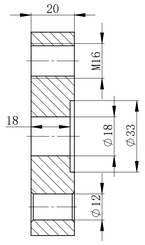




# 底座安装接口
# Robot base mounting dimension
View Scale 1 : 3

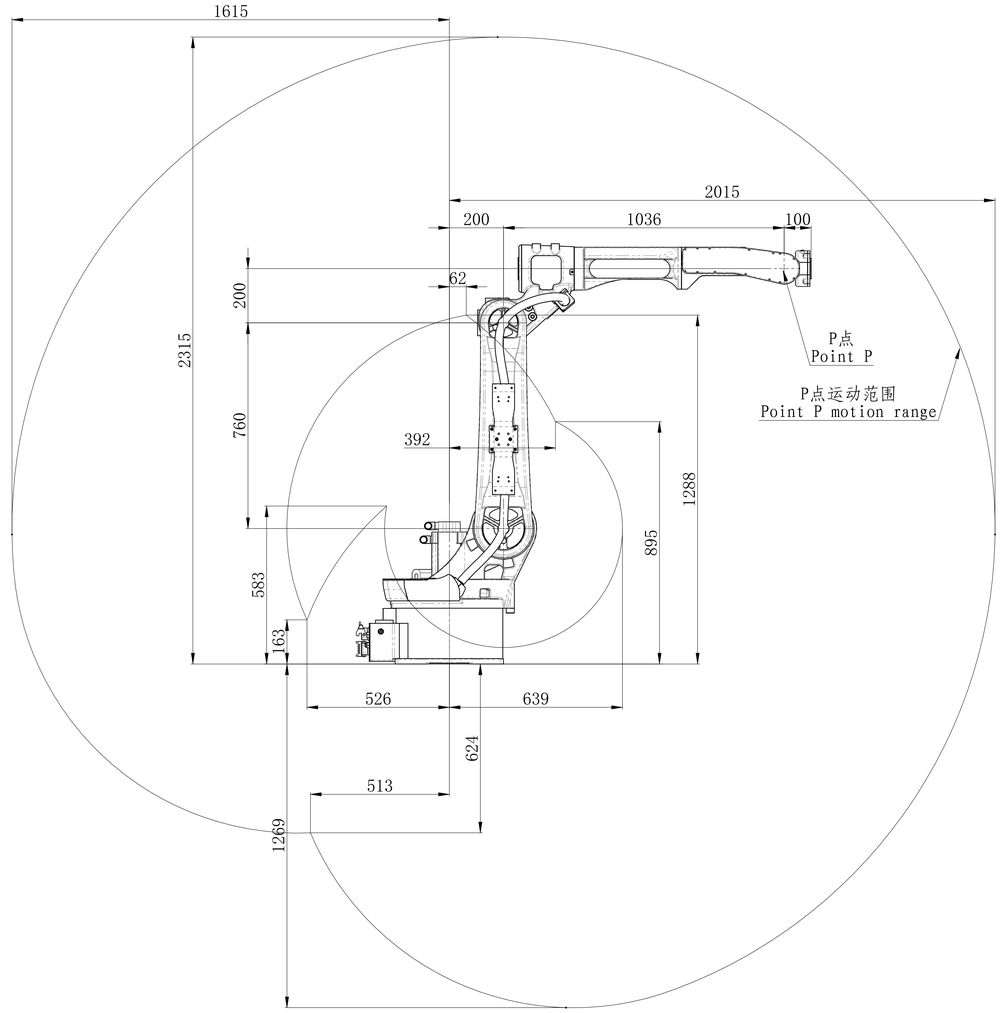


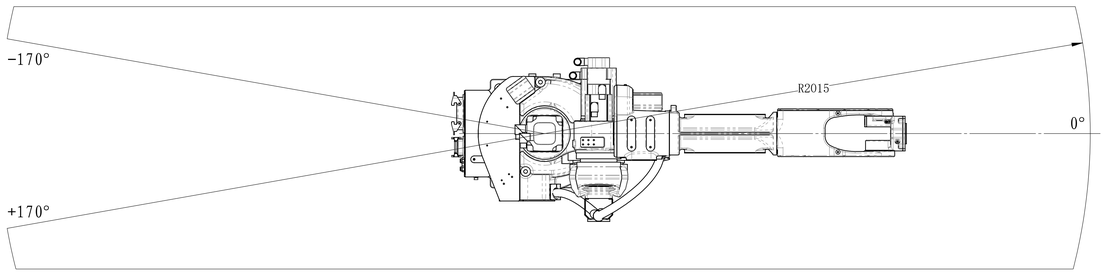




视图D
1 : 1
D-D
1 : 1




# 运动范围图
# Motion range




| | | |
|---|---|---|
| 图幅 SIZE | 比例 SCALE | 南京埃斯顿机器人工程有限公司 ESTUN Robotics Co.,Ltd |
| A0 | 1:6 | 运动空间包络图 Motion space envelop diagram |
| 共 1 页 第 1 页 SHEET 1 OF 1 | | 1ER12-2000-HW |

| |
|---|
| 借用件登记 |
| 描图 |
| 校描 |
| 旧底图总号 |
| 签字 |
| 日期 |